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#### INSTALLATION INSTRUCTIONS: MCD DEVICENET MODULE

Order Code: 175G9002

### **1. Important User Information**

Observe all necessary safety precautions when controlling the soft starter remotely. Alert personnel that machinery may start without warning.

It is the installer's responsibility to follow all instructions in this manual and to follow correct electrical practice.

### 2. Installation

#### CAUTION

Remove mains and control voltage from the soft starter before attaching or removing accessories. Failure to do so may damage the equipment.

Install the DeviceNet Module using the following procedure:

- 1. Remove control power and mains supply from the soft starter.
- 2. Attach the module to the soft starter as illustrated.
- 3. Set the DeviceNet Module Node Address (MAC ID) and Data Rate.
- 4. Apply control power to the soft starter.
- 5. Insert the network connector into the module and power up the DeviceNet network.

### 2.1. Physical Installation

- 1. Fully pull out the top and bottom retaining clips on the module.
- 2. Line up the module with the comms port slot.
- 3. Push in the top and bottom retaining clips to secure the module to the starter.



Remove the module using the following procedure:

- 1. Take the module off-line.
- 2. Remove the DeviceNet connector.
- 3. Remove control power and mains supply from the soft starter.
- 4. Fully pull out the top and bottom retaining clips on the module.
- 5. Pull the module away from the soft starter.



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#### CAUTION

Network designs must decrease the maximum allowable cumulative dropline length by 400 mm for every module installed on the network. Failure to do so may result in network communication errors and decreased reliability.

Example: ODVA specifies a maximum cumulative dropline length of 156 m on a network operating at 125 kb/s. If six modules were installed on this network, the total cumulative dropline length would need to be decreased to 153.6 m.

# **3.** Configuration

The DeviceNet Module is a Group 2 slave device, using a predefined master/slave connection set. I/O data is produced and consumed using polled I/O messaging.

The soft starter must be added to the DeviceNet manager project using the EDS file and configuration/management software tool. This file is available from <u>www.danfoss.com/drives</u>. In order to operate successfully, the correct EDS file must be used. An on-screen graphics bitmap file (device.bmp) is also available.

### 4. Adjustment

The factory default settings for the rotary adjustment switches are:



Changes to the rotary switch settings take effect when the DeviceNet network is next powered up.



#### N.B.!:

The Data Rate and Node Address (MAC ID) must be set locally on the module. These cannot be set using DeviceNet management software.

When the Data Rate and MSD Node Address (MAC ID) rotary switches are set on PGM position, the module uses the previously used valid on-line Data Rate and Node Address (MAC ID).

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## 5. Connection

MCD 200: For the MCD DeviceNet Module to accept serial commands, a link must be fitted across terminals A1-N2 on the soft starter.

In order for the MCD 500 to accept commands from the serial network, the soft starter must be in Auto On mode and links must be fitted to terminals 17, 18 and 25, 18.

In Hand On mode, the starter will not accept commands from the serial network but the starter's status can still be monitored.



1	MCD 200	1	MCD 500 (Auto On mode)		
			17, 18: Stop		
			25, 18: Reset		
2	MCD DeviceNet Module	2	MCD DeviceNet Module		
3	Standard connection onto DeviceNet network	3	Standard connection onto DeviceNet network		



#### N.B.!:

If MCD 500 parameter 3-2 *Comms in Remote* is set to Disable Comms in Remote, the starter will not accept start or stop commands from the serial network (the starter will still accept reset commands and allow status monitoring).

### 6. Module and Network LEDs

The Module LED indicates the condition of the power supply and module operation.

The Network LED indicates status of the communication link between the DeviceNet Module and the network Master.



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LED	State	Description
(1)	Off	Network power off
(Module)	Green	Normal operation
	Red	Unrecoverable fault
	Red/Green flashing	Self Test mode
(2)	Off	Duplicate MAC ID test has not been completed
(Network)	Green flashing	Online but no connection with Master
( /	Green	Online and allocated to a Master
	Red flashing	One or more timed out I/O connections
	Red	Failed communication between module and Master
	Red/Green flashing	Communication faulted and received an Identity
		communication faulted request



#### N.B.!:

When a communications failure occurs, the soft starter may trip if the Communication Timeout parameter for the network is set greater than zero. When communication is restored, the soft starter must be reset.

# 7. DeviceNet Polled I/O Structure

Once the EDS file has been loaded, the DeviceNet Module must be added to the scanner list with parameters shown in the following table:

Parameter	Value
I/O connection type	Polled
Poll receive size	14 bytes
Poll transmit size	2 bytes

Once the soft starter, module and Master have been set up, configured and powered up, the Master will transmit 2 bytes of data to the module and receive 14 bytes of data from the module.

Byte	Bit	Function	
0	0	0 = Stop command	
		1 = Start command	
	1	0 = Enable Start or Stop command	
		1 = Quick Stop (i.e. coast to stop) and disable Start command	
	2	0 = Enable Start or Stop command	
		1 = Reset command and disable Start command	
	3 to 7	Reserved	
1	0 to 1	0 = Use soft starter remote input to select motor set	
		$1 =$ Use primary motor set when starting $^{1}$	
		2 = Use secondary motor set when starting $^{1}$	
		3 = <i>Reserved</i>	
	2 to 7	Reserved	

Master > Slave polled I/O output data is as follows:

<sup>1</sup> Ensure that the programmable input is not set to Motor Set Select before using this function.

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Byte	Bit	Function	Value		
0	0	Trip	1 = Tripped		
	1	Warning	1 = Warning		
	2	Running	0 = Unknown, not ready, ready to start or tripped		
			1 = Starting, running, stopping or jogging		
	3	Reserved			
	4	Ready	0 = Start or stop command not acceptable		
			1 = Start or stop command acceptable		
	5	Control from Net	1 = Always except in Program mode		
	6	Local/Remote	0 = Local control		
			1 = Remote control		
	7	At reference	1 = Running (full voltage at the motor)		
1	0 to 7	Status	0 = Unknown (menu open)		
			2 = Starter not ready (restart delay, thermal delay		
			or run simulation)		
			3 = Ready to start (including warning state)		
			4 = Starting or running		
			5 = Soft stopping		
			7 = Trip		
			8 = Jog forward		
			9 = Jog reverse		
2	0 to 7	Trip/Warning code	See trip code table.		
3	0	Initialised	$1 =$ Phase sequence bit is valid (bit 1) after $1^{st}$		
		Discourse	start		
	1	Phase sequence	1 = Positive phase sequence detected		
. 1	2 to /	Reserved			
4 <sup>1</sup>	0 to 7	Motor current (low byte)	Current (A)		
5 1	0 to 7	Motor current (high byte)			
6	0 to 7	Current %FLC (low byte)	Current as a percentage of soft starter FLC setting		
7	0 to 7	Current %FLC (high byte)	(%)		
8	0 to 7	% Motor 1 temperature	Motor 1 thermal model		
9	0 to 7	% Motor 2 temperature	Motor 2 thermal model		
10	0 to 7	% Power factor	Percentage power factor		
			(100 = power factor of 1)		
11	0 to 7	Power (low byte)	Power low byte, scaled by power scale		
12	0 to 3	Power (high nibble)	Power high nibble, scaled by power scale		
	4 to 5	Power scale	0 = Multiply power by 10 to get W		
			I = Multiply power by 100 to get w		
			2 = POWer (KW) 3 = Multiply power by 10 to get kW		
	6 to 7	Pacarvad			
12	0.107	Disitel Input state	0 Start (0 anan 1 slagad)		
12	0 to 3	Digital Input State	v = Start(v = open, 1 = Closed)		
			1 - Stop 2 - Posot		
			$2 - \pi c s c l$ 3 - Input A		
	4 + 2 7	Deserved			

Slave > Master polled I/O input data is as follows:

4 to 7 *Reserved*<sup>1</sup> For models MCD5-0428C and smaller this value will be 10 times greater than the value displayed on the LCP.

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### 7.1.1. Trip Codes

Code	Тгір Туре	MCD 201	MCD 202	MCD 500
0	No trip			
11	Input A trip			
20	Motor overload (thermal model)			
21	Heatsink overtemperature			
23	L1 phase loss			
24	L2 phase loss			
25	L3 phase loss			
26	Current imbalance			
28	Instantaneous overcurrent			
29	Undercurrent			
50	Power loss/Power circuit			
54	Phase sequence			
55	Frequency (Mains supply)			
60	Unsupported option (function not available in inside delta)			
61	FLC too high (FLC out of range)			
62	Parameter out of Range			
70	Miscellaneous			
75	Motor thermistor			
101	Excess start time			
102	Motor connection			
104	Internal fault $x$ (where $x$ is the fault code detailed in the table below).			
113	Starter communication (between module and soft starter)			
114	Network communication (between module and network)			
115	L1-T1 shorted			
116	L2-T2 shorted			
117	L3-T3 shorted			
119*	Time-overcurrent (Bypass overload)			
121	Battery/clock			
122	Thermistor circuit			

★ For MCD 500, time-overcurrent protection is only available on internally bypassed models.

The table below details the internal fault code associated with trip code 104.

Internal	Message displayed on the LCP
fault	
70 ~ 72	Current Read Err Lx
73	Power On in Simulation mode
74 ~ 76	Motor connection Tx
77 ~ 79	Firing fail SCRx
80 ~ 82	VZC Fail Px
83	Low Control Volts
84 ~ 98	Internal fault X
	Contact your local supplier with the fault code (X).

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# 8. Parameter Object

The DeviceNet Module supports parameter objects through explicit messaging. Soft starter parameters can be uploaded (written) and downloaded (read) using DeviceNet management software. When the DeviceNet Module is powered up, it automatically obtains parameter information from the soft starter.

Detail	Value (Hex)	Comment
Class	0F	Parameter object address
Instance	$1 \sim xxx$	xxx = maximum soft starter parameter number
Attribute ID	01	Always 0x01
Get Service	0E	Read single soft starter parameter value
Set Service	10	Write single soft starter parameter value



#### N.B.!:

Only available on MCD 500 soft starters. For parameter details, see the soft starter User Manual.

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# 9. Specifications

Enclosure
Dimensions
Weight
Protection IP20
Mounting
Spring-action plastic mounting clips (x 2)
Connections
Soft starter
Network
Maximum cable size
Contacts Gold flash
Settings
Node address (MAC ID)
Setting Rotary switches
Range 0 to 63 (63, factory default)
Data rate
Setting Rotary switch
Options 125 kB, 250 kB, 500 kB (125 kB, factory default)
Power
Consumption
steady state
in-rush (at 24 VDC) for 2 ms
Galvanically isolated
Certification
CE IEC 60947-4-2

